

This readme.txt file was generated on 2020-12-15 by Isaiah Taylor

The files included in the “R\_analysis” directory include the code and data required to reproduce the statistical analysis in Taylor and Lehner, et al, “Mechanism and function of root circumnutation” (doi: <https://doi.org/10.1101/2020.05.04.075127>).

## GENERAL INFORMATION

1. Title of Dataset: Data and scripts from: Mechanism and function of root circumnutation

2. Author Information

### A. Principal Investigator Contact Information

Name: Isaiah Taylor

Institution: Duke University

ORCID: 0000-0002-6535-8658

Email: [iwt@duke.edu](mailto:iwt@duke.edu)

3. Date of data collection (single date, range, approximate date): 2018-2020

## SHARING/ACCESS INFORMATION

1. Licenses/restrictions placed on the data: Data available under a CC0 waiver

2. Links to publications that cite or use the data: Taylor and Lehner, et al, “Mechanism and function of root circumnutation” (doi: <https://doi.org/10.1101/2020.05.04.075127>)

## DATA & FILE OVERVIEW

1. File List:

Each folder is a separate analysis included an Rproj file which can be loaded. The scripts directory contains a runner script that will use the “here” library to find the data in the “data” directory for seamless loading. The exception is the “05\_gene\_expression” folder which only contains gene expression count matrices for RNA-Seq experiments.

## METHODOLOGICAL INFORMATION

1. Description of methods used for collection/generation of data:

See preprint at <https://doi.org/10.1101/2020.05.04.075127> for methodological description.

2. Methods for processing the data:

See preprint at <https://doi.org/10.1101/2020.05.04.075127> for data processing description.

3. Instrument- or software-specific information needed to interpret the data:

R, version > 3.7

Libraries: ggplot2, here, splines, readxl, aod,

DATA-SPECIFIC INFORMATION FOR: All data files are described below

**all\_tip\_tracking\_combined.csv** - used as the input data for 02, 03

Column definitions:

plant = experiment number and the specific plant

BX and BY = Tip coordinates

range = the frames after germination recorded (1\_192 means frames 1-192, and since each frame represents 1/4 of an hour,  $192 * 1/4 = 48$  hours of measurements)

uid = unique identifier corresponding to the plant and the range

line = experiment number

**01\_root\_length folder**

data file: wt\_mutant\_length\_position.csv

Column definitions:

plant = individual root measurements

root\_length = root length in mm

genotype = genotype

x\_beg = x coordinate in image (pixel) of the base of root

x\_end = x coordinate in image (pixel) of the tip of root

y\_beg = y coordinate in image (pixel) of the base of root

y\_end = y coordinate in image (pixel) of the tip of root

#### **04\_cell\_length**

data files: Analysis\_MUT\_final\_graphs.xlsx, Analysis\_WT\_final\_graphs.xlsx

We create a dataframe with the following columns:

midline\_distance = distance of the cell along the middle path of the root where the cell is located (um)

length = length of the cell (um)

side = inner or outer

root = root, numbered 1-9

angle = the measured angle of the root

angle\_start = the distance along the midline that is considered the maximal bend.

#### **05\_gene\_expression**

data files: hk1\_plus\_minus\_tZ\_CPM\_edgeR.csv, WT\_hk1\_CPM\_edgeR.csv

#### **06\_surface\_exploration**

data file: logistic\_data.csv

Column definitions:

Y\_success = success or failure in growing through within 72 hours of striking the surface

Genotype = wildtype or hk1 mutant

Spacing = distance between holes in platform= 5, 7, 9, or 11 mm

### **07\_nutation\_robot**

data file: angles.csv

Column definitions:

type = "off" (non-nutating) or "on" (nutating)

angle = angle of the robot upon striking peg

success = 1 (success) or 0 (failure)

### **08\_gravel\_penetration**

data file: gravel\_success.csv

Column definitions:

box = specific experiment number

genotype = genotype

germinated = number of seeds that germinated

thru\_72hr\_pg = number of seeds that successfully passed through the gravel

expt = experimental replicate